

An Efficient Hybrid Model to Solve Linear Programming Problems Using Artificial Neural Network

L.R.Aravind Babu¹ and Dr.K.Venkatachalapathy²

¹Assistant Professor, Department of Information Technology,
Faculty of Engineering & Technology, Annamalai University
Contact: er.arvee@rediffmail.com

²Professor, Department of Computer and Information Science,
Faculty of Science, Annamalai University.

Abstract—Linear Programming Problems are mathematical models used to represent real life situations. Linear Programming problems arise in real-life economic situations where profits are to be maximized or costs to be minimized. When formulating an Linear Programming (LP) model, systems analysts and researchers often include all possible constraints although some of them may not be binding at the optimal solution. The presence of redundant constraints does not alter the optimum solution(s), but may consume extra computational effort. Redundant constraints identification methods are applied for reducing computational effort in LP problems. But accuracy of the Linear Programming problems goes down due to this reduction of loops and constraints. To achieve optimality in accuracy and also in computational effort, we propose an algorithmic Structure, called Hybrid Model, it trains the constraint and parameter using artificial neural network before applying the formal methodology.

Keywords: Linear Programming, ANN (Artificial Neural Network), Redundant Constraints, Load Forecasting, Training Parameters.

1. Introduction

Linear programming problems arise in a wide variety of scientific and engineering fields including regression analysis, function approximation, signal processing, image restoration, parameter estimation, filter design, robot control, etc. Linear Programming Problems are mathematical models used to represent real life situations in the form of linear objective function and constraints various methods are available to solve linear programming problems. When formulating an LP model, systems analysts and researchers often include all possible constraints

although some of them may not be binding at the optimal solution. The presence of redundant constraints does not alter the optimum solution(s), but may consume extra computational effort. Many researchers have proposed algorithms for identifying the redundant constraints in LP models. The widely used methodology for LP problems is the revised simplex method, a univariate search technique. It suffers the drawback of slow convergence with the tendency of variable popping in and out of the basis matrix. The number of iterations are more and increase in computational effort and time. This gives wide scope to a search of new algorithm. In the bounded complex algorithm [12] a univariate search technique is adopted, but the entering variables are arranged not only based on the maximum contribution of that variable to the objective function but also on the type of the constraints. Once the priority arrangement of the promising variables is obtained the iterations are performed as in the Simplex Method by selecting a leaving variable based on bounds of the variables. Redundancies, if any, in the LP model will waste computational effort. In fact, there is a wide literature on the detection and elimination of redundant constraints in LP models [1–11]. Heuristic approach [13] is using an intercept matrix to identify redundant constraints prior to the start of the solution process. In this heuristic approach, tendency of variables to pop in and pop out of the basis is eradicated after eliminating the redundancies. The eradication of pop-in and pop-out substantially reduces the number of iterations. A significant reduction in the computational effort is achieved for LP problems of different sizes in heuristic approach.

2. Related works

Redundant Constraints and Complex Bounded Algorithm

2.1 Complex Algorithm

Very often a linear programming problem may have some or all variables bounded with lower and upper limits in addition to the given constraints. The lower and upper limits can represent the minimum and maximum demands for certain products to solve this kind of these problems a special kind of technique known as a bounded variable simplex method is available. A new algorithm is presented to solve linear bounded variable problems whose constraint coefficient is non-negative. In this method the variables are arranged according to their total contribution to the objective function as was done in solving linear programming problem.

1. If any variable has a lower bound. Then substitute $X^1 = L + X$.
2. Determination of entering Vector P_j

$$Z_j - C_j = (1C_B B^{-1}) \begin{pmatrix} -C_j \\ P_j \end{pmatrix}$$

If the objective function is maximization a variable having $(Z_j - C_j)$ value as negative is Promising variable. If the objective function is maximization a variable having $(Z_j - C_j)$ value as positive is Promising variable.

3. Determination of leaving vector P_r when the entering vector is P_j and the current basis matrix B_c , the leaving vector must correspond to a $\theta_o = \min [\theta_1, \theta_2, \mu_j]$ where

$$\theta_1 = \min_k \left(\frac{B^{-1}P_o}{\alpha_{kj}}; \alpha_{kj} > 0 \right)$$

where $\alpha_{kj} = B^{-1}P_j$, $K = 1, 2, \dots, m$

$$\theta_2 = \min_k \left(\frac{\mu_k - (B^{-1}P_o)}{\alpha_{kj}}; \alpha_{kj} < 0 \right)$$

4. After selecting the leaving variable using the above condition the changes in the current basis solution can be effected as follows:

(a) If $\theta = \theta_1$ which correspond $i = r$ than variable X_j enters the basis while the variable corresponds to $(B^{-1}P_o)_r$ leaves the basis. Update M^{-1} using step 5.

(b) If $\theta = \theta_2$ then X_j enters the basis and the variable $(B^{-1}P_o)_r$ leaves the basis. When $(B^{-1}P_o)_r$ is non-basic, its value must be zero. To achieve this put $(B^{-1}P_o)_r = \mu_r - (B^{-1}P_o)_r^1$ and P_o becomes $P_o^1 = P_o - \mu_j P_j$ and update M^{-1} using step 5.

c) If $\theta = \mu_j$ then put $X_j = \mu_j - X_j^1$ then entering variable is non-basic at $X_j = \mu_j$, there is no variable leaving the basis. But it creates the following changes $P_j^1 = P_j$ and P_o becomes $P_o - \mu_j P_j$ and $Z_j - C_j = Z_j - C_j$.

5. Construction of M^{-1}

Obtain the column vector η for the leaving X_j defined by

$$\eta = \begin{bmatrix} Z_j C_j \\ B^{-1} P_j \end{bmatrix}$$

6. If the list of ordered variable is exhausted then go to step 7, else go to step 2.

7. If any vector enters at its upper bound take the negated column then go step 2, else terminate the process.

2.2. Identification of Redundant constraints

Redundant constraints are the constraints that can be omitted from a system of linear constraints without changing the feasible region.

Consider the following system of m linear inequality constraints and n variables ($m \geq n$):

$$AX \leq b, X \geq 0 \quad (1)$$

where $A \in R^{m \times n}$, $b \in R^m$, $X \in R^n$ and $0 \in R^n$.

The feasible region S associated with system (1) is defined

$$S = \{X \in R^n / AX \leq b, X \geq 0\}.$$

Redundant constraints in system (1) do not play a role in determining the feasible region S .

To define redundant inequality constraints more formally, we denote for any fixed $k \in (1, 2, 3, \dots, m)$, $S_k = \{X \in R^n / A_i X \leq b_i, X \geq 0 \forall i \neq k\}$.

The k th constraint $A_k X \leq b_k$ ($1 \leq k \leq m$) is a redundant inequality in system (1) if and only if $S_k = S$.

3. Proposed Algorithm for optimality to improve the accuracy with training and learning of parameters and constraints using ANN.

A most excellent algorithm must be optimal in both computational effort and accuracy. All the above methodologies concentrated only on achieving best computational effort. Whereas accuracy of these systems may go down due to reducing number of constraints and number of iteration. To achieve optimality in computational effort and also in accuracy, we proposed a hybrid algorithmic structure. If we reduce number of iterations, the time complexity become optimal, but

the accuracy of the system has reduced. To improve the accuracy, we suggested training and learning of parameters and constraints. This training is possible in real world application by applying artificial neural network (ANN). The ANN has applied for various applications to predict forecasting of parameters, constraints and also to obtain optimality in real world parameters. To proceed further, we consider a real world application, for ex. Load forecasting. Load forecasting is essential in the electricity market for the participants to manage the market efficiently and stably. However, the electric power load forecasting problem is not easy to handle due to its nonlinear and random-like behaviors of system loads, weather conditions, and variations of social and economic environments, etc. Many studies have been reported to improve the accuracy of load forecasting using the conventional methods such as regression-based method [14], Kalman filter [15], and knowledge-based expert system [16]. However, these techniques have a possibility to lack the accuracy of prediction with the higher load forecasting errors in some particular time zones, which are, for example, the weekdays of the summer season, weekend, and/or Monday. To overcome this problem, the computational intelligence techniques [16]–[24], which are the fuzzy systems and artificial neural networks [19, 22, 27], have been investigated in the past decade as an alternative to the conventional methods.

3.1 Existing Algorithm

Step 1). If the predicted day is belonging to a summer season, go to step 4). Otherwise, it is the day on spring, fall, or winter seasons.

Step 2). Construct input information using the load data during three days (which are subject to Monday through Friday) before the predicted day.

Step 3). Forecast the maximum load using the exponential smoothing method.

Step 4). In case that the predicted day belongs to a summer season, the temperature sensitivities are computed using the variations of the load and temperature between the predicted day and its one previous day.

Step 5). Forecast the maximum load with the temperature sensitivities calculated in step 4). After taking the above steps, the normalized value of the 24 hourly loads is calculated from the data obtained from the load during the previous three weeks of the predicted day. Thereafter, the 24 hourly loads of the day are forecasted from the normalized value.

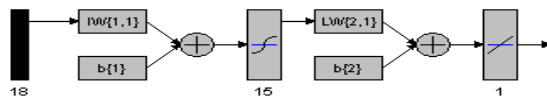


Figure.1 Shows Neural Network for Load Forecasting

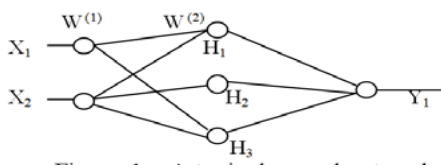


Figure.2Shows a Typical Neural Network

3.2 Our Proposed Algorithm(Structure)

Step 1). If the predicted day / time are belonging to class-1environment, go to step 4. Otherwise, it is class-2environment.

Step 2). Construct input information using the inputparameters and constraints using any formal or conventionalmethods like complex algorithm and or identifying redundantconstraints before the predicted day or time.

Step 3). Forecast the appropriate parameters.

Step 4). In case that the predicted day or time belongs to aclass-1 situation, the value of parameters may vary.

Step 5). Forecast the appropriate parameters with thephysical sensitivities calculated in step 4. After taking theabove steps, the normalized value of parameters is calculatedfrom the data obtained. Thereafter, the parameters for anyclass of situation are forecasted from the normalized value.

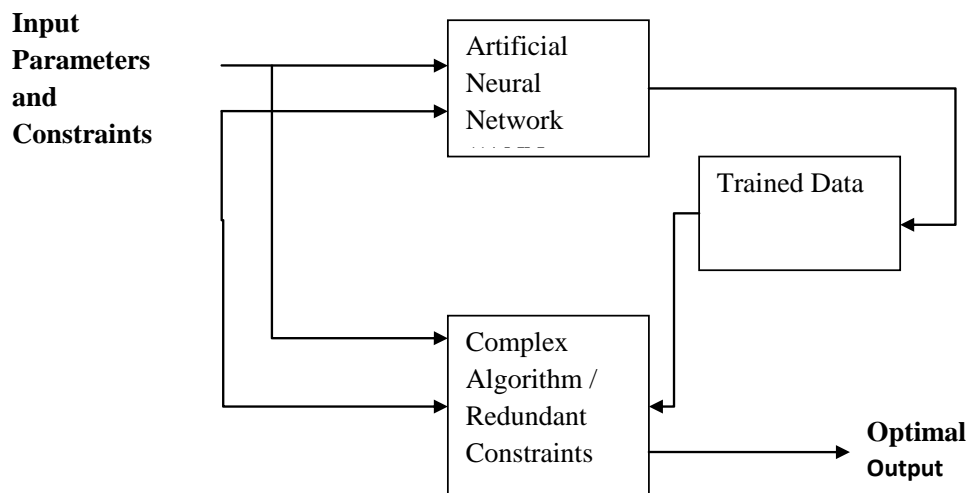


Figure.3 Shows block diagram of the Proposed Method

4. Results of the proposed method with training and learning(parameters and constraints) by applying ANN

The proposed a hybrid structure that improves the accuracy of bounded variables in linear programming problem model by suggesting the training and learning of parameters and constraints. This training is possible in real world application by applying artificial neural network. We believe, the proposed hybrid structure shows increased performance in accuracy.

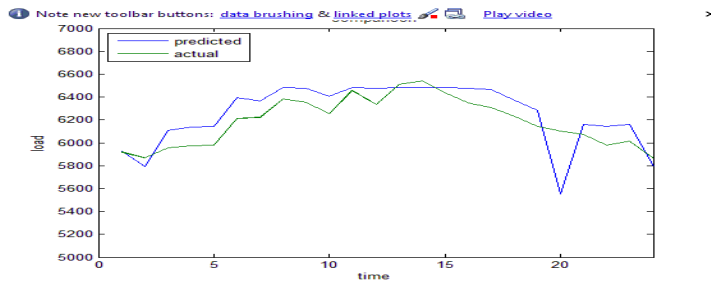


Figure.4 shows the testing phase with trained and learned values for optimization.

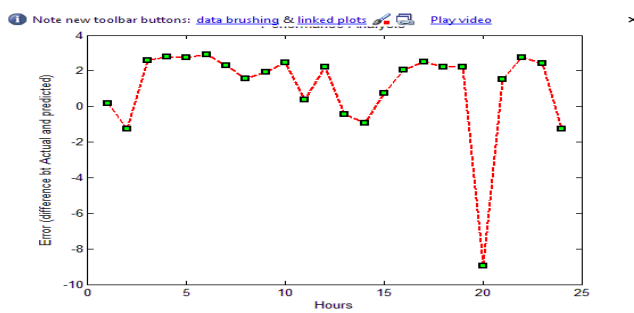


Figure.5 shows error plot difference between actual and predicted values

5. Conclusion

The Hybrid Structure that improves the accuracy of bounded variables in Linear Programming Problem model by suggesting the training and learning of parameters and constraints. The Training is possible in applications by applying Artificial Neural Network. We believe, the proposed structure shows increased performance in accuracy. The Hybrid Algorithmic Structure must be optimal in both computational effort and accuracy. All the above methodologies concentrated only on achieving best computational effort. Whereas, accuracy of these systems may go down due to reducing number of constraints and number of iteration. To achieve optimality in computational effort and also in accuracy, we proposed a Hybrid Algorithmic (model) to improve the accuracy of variables in any Linear Programming Problems.

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